

interactive



Accident avoidance by active intervention for Intelligent Vehicles

www.interactIVe-ip.eu

interactIVe – Challenges

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Project overview: Facts

- Budget: EUR 30 Million
- European Commission: EUR 17 Million
- Duration: 47 months (January 2010 – November 2013)
- Coordinator: Aria Etemad, Ford Research and Advanced Engineering Europe
- 10 Countries: Czech Republic, Finland, France, Germany, Greece, Italy, Spain, Sweden, The Netherlands, UK



European Commission
Information Society and Media



Consortium

- OEMs



- Suppliers



- Research



- SMEs



Mission

The interactive vision:
Accident-free traffic and active safety systems in all vehicles.

- **Overcome the obstacle of independent functions and high system costs:**
 - Integrated solutions
 - Affordable systems
- **Consider all vehicle classes:**
 - Build up seven demonstrator vehicles: six passenger cars & one truck

Causes of accidents

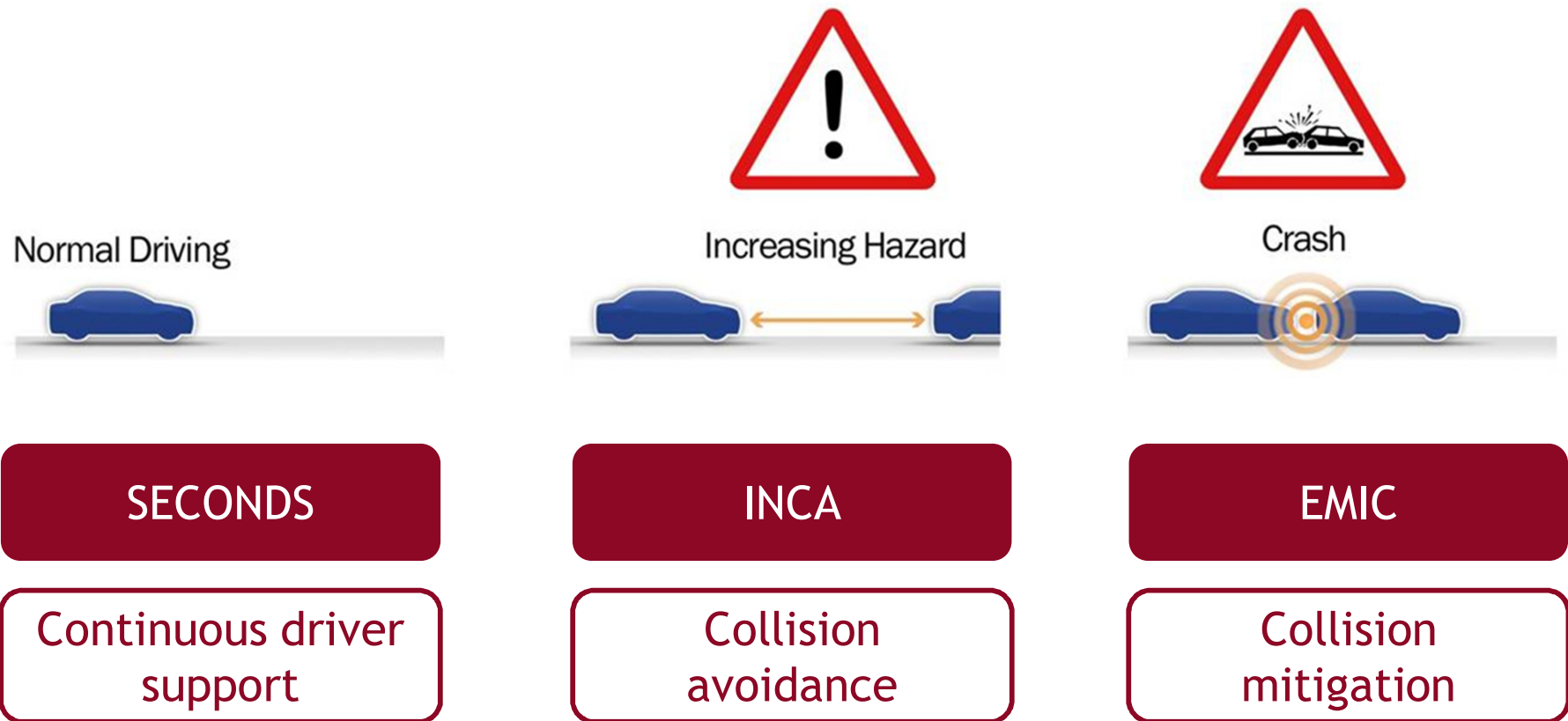
Human Error > 90%



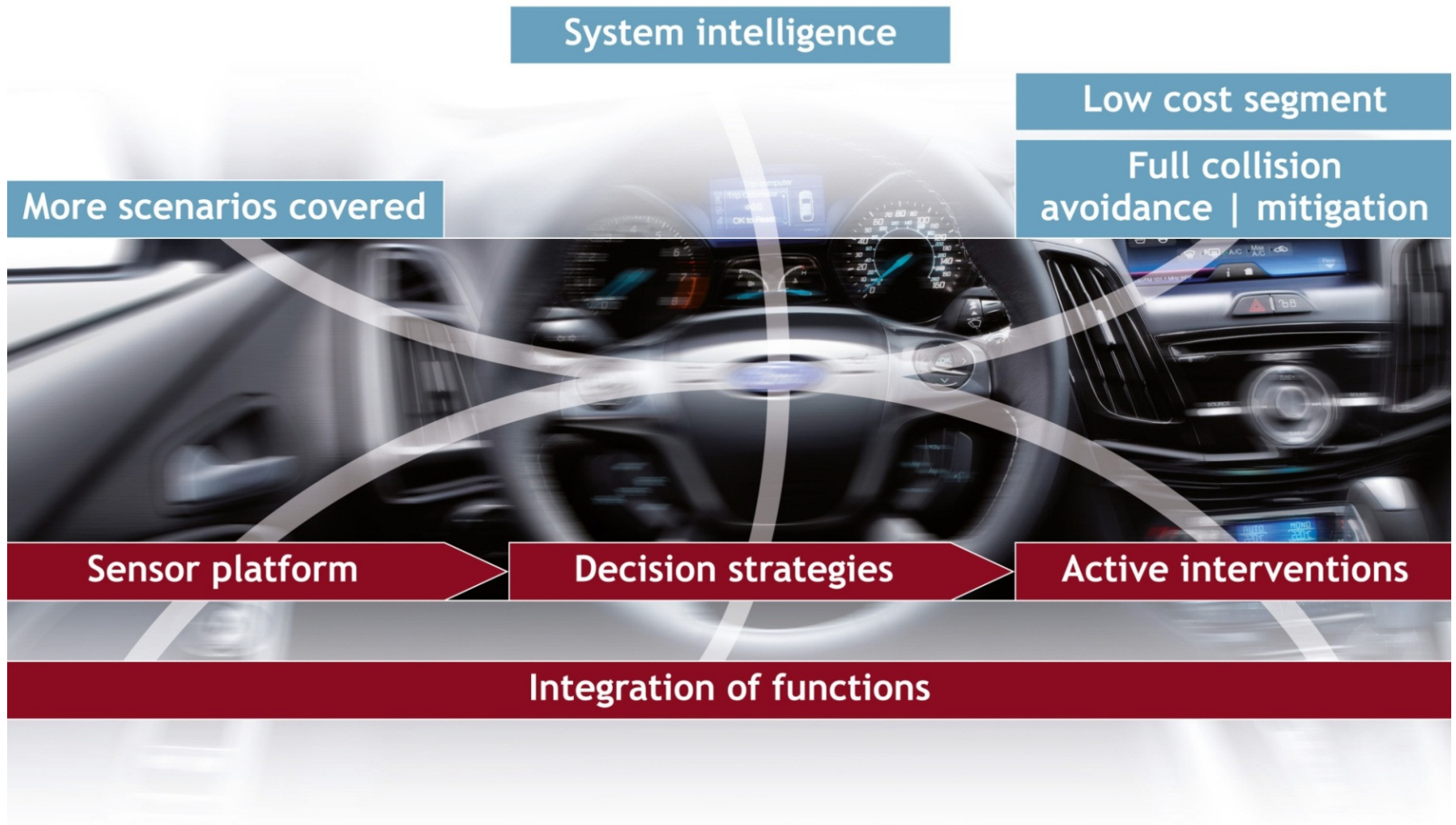
Others
(e.g. surroundings, weather, ...)

Source: GIDAS Database

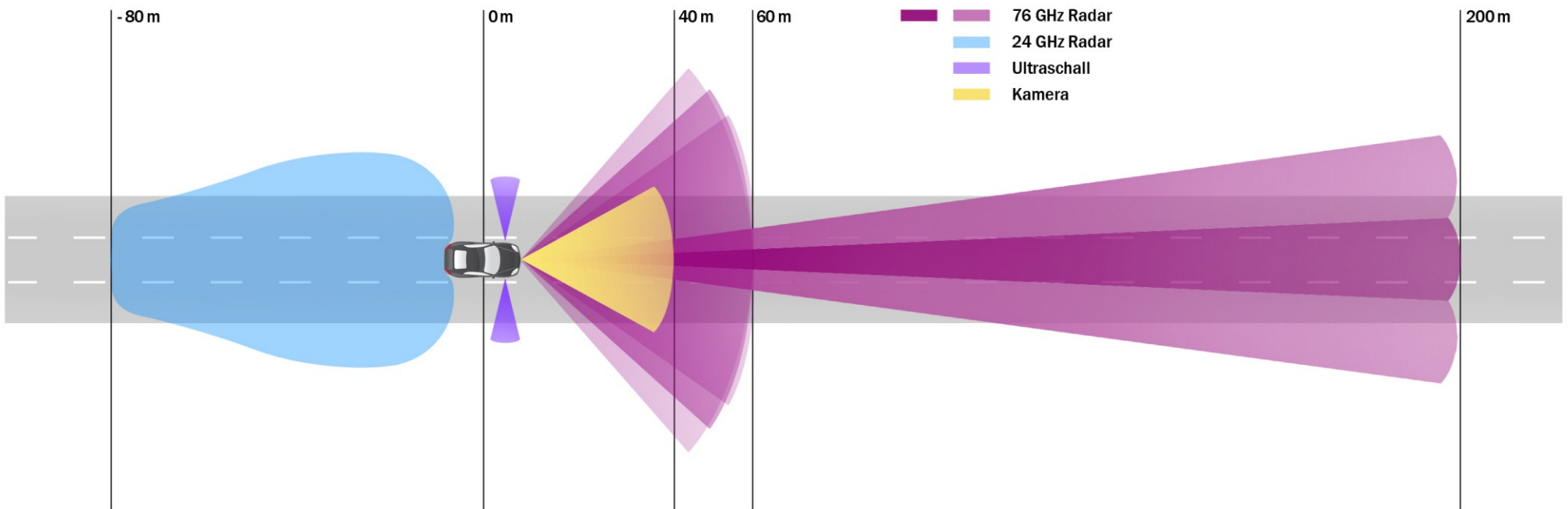
Research concept



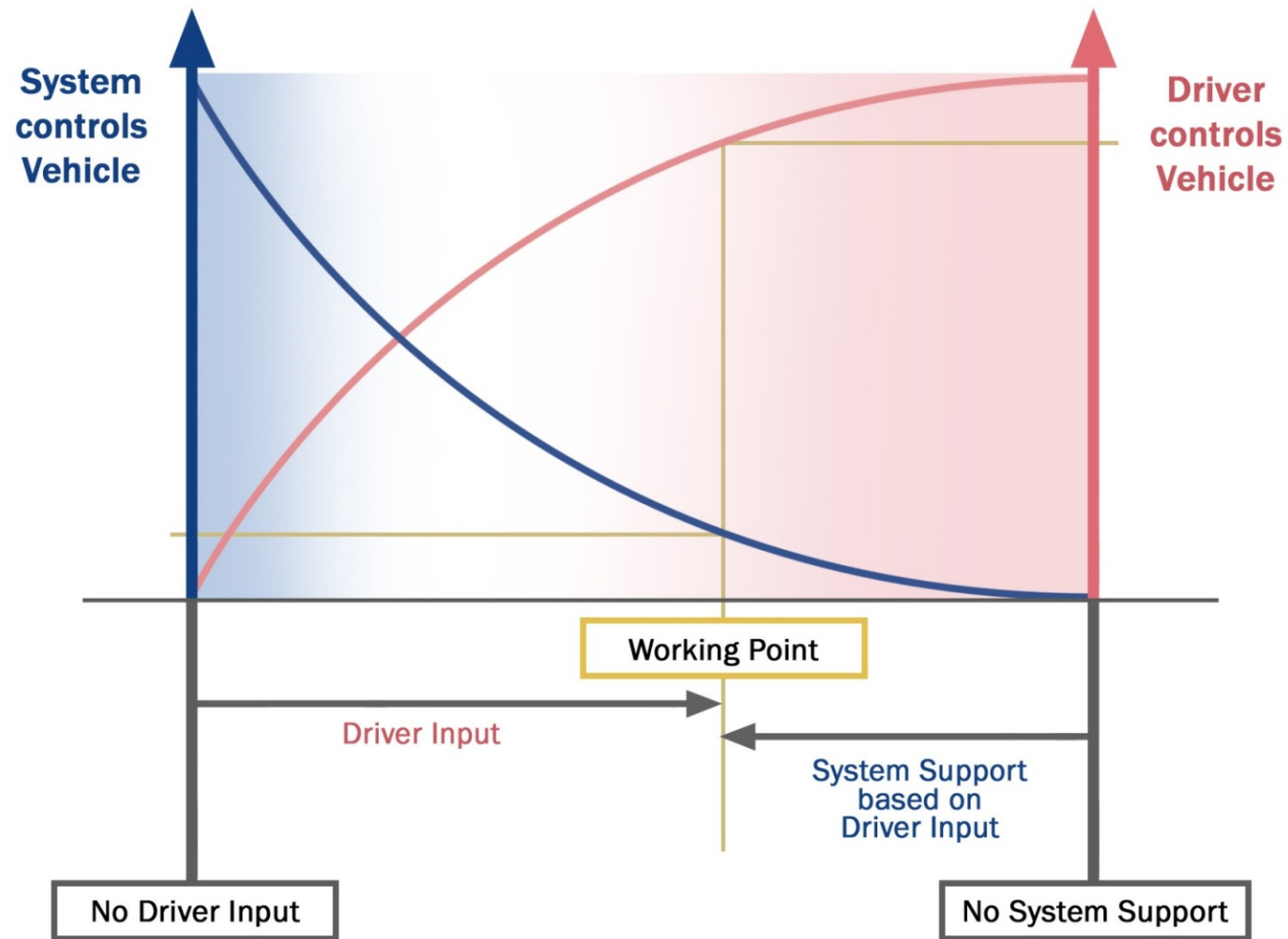
Objectives



Sensor concept



Support: splitting driving task between driver and vehicle



Seven demonstrator vehicles

SECONDS

INCA

EMIC

BMW

Enhanced dynamic pass predictor

Fiat

Continuous support with focus on haptic HMI solutions

Volvo car

Collision avoidance, continuous support and SafeCruise

Ford

Collision avoidance, continuous haptic support and automated driving

Volvo truck

Collision avoidance and run-off road prevention by braking and steering, stability considerations for heavy vehicles

VW

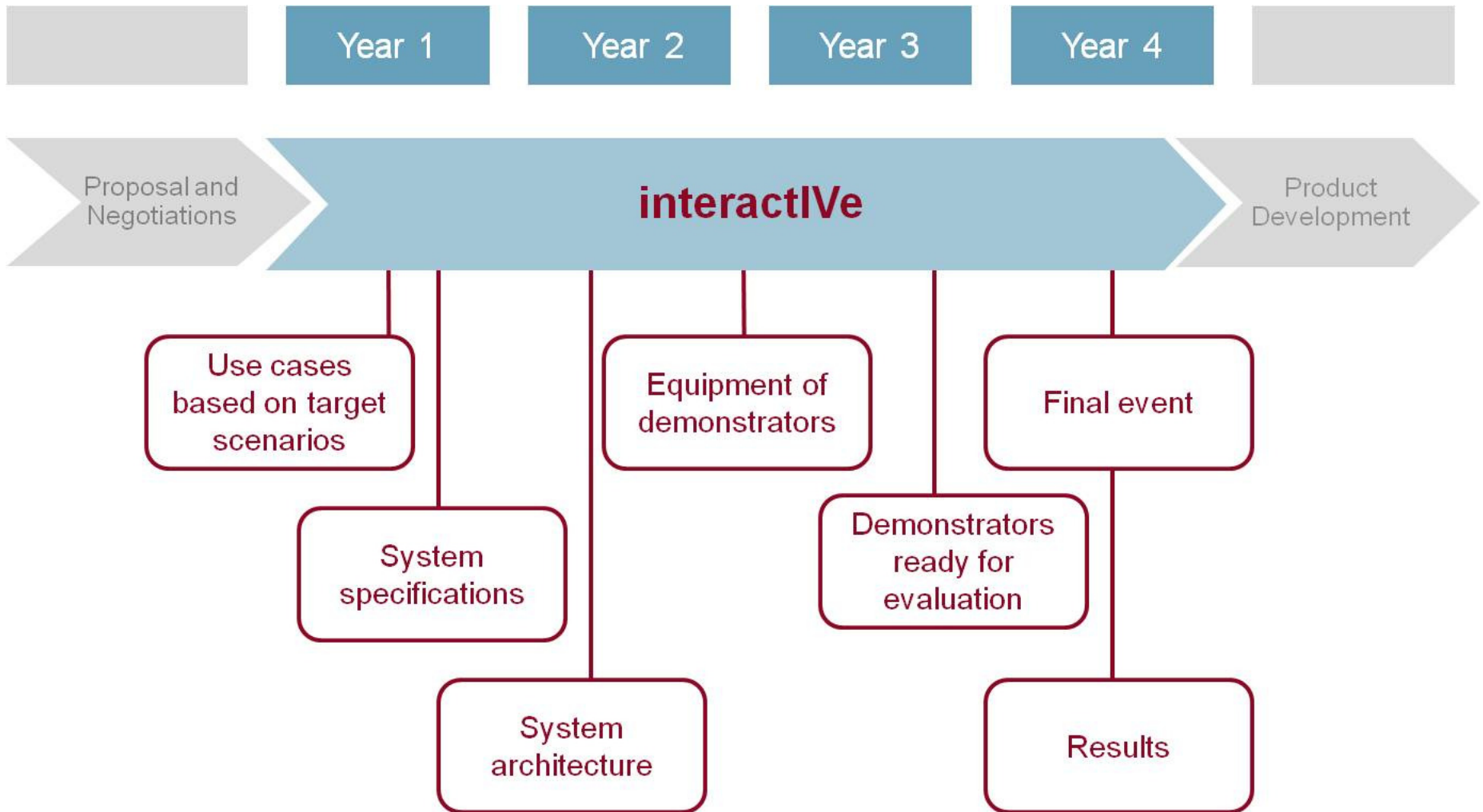
Collision mitigation with focus on cost-efficient sensors and algorithm approach

Conti

Emergency steering assistance with focus on radar/vision combination



Timeline



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Thank you.

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